

















TOHO ELECTRONICS INC.

# DIGITAL TTM-200

## Features

- •Improvement of the controllability with new PID algorithm
  - ①Time until it is stabilized from a control start is shortened
- ②Loading the jump less control which controls the overshoot after the disturbance
- ③You can chose from three kind of PID control that can be chosen ●Full multiple inputs

Established the input specification to be one type of the thermocouple (13 types), the platinum resistance temperature sensor (2 types), voltage (5 types) and the electric current (1 type). (Modification of setting with parameter)

- Sampling period
- Realized acceleration in 200mS
- Utilizes a liquid crystal display
- ①The indication range has been extended to present 5 columns ②Actualized the various indication with 11 segments ③Adopted LED to back light
- ●PV color auto-change

Display color of Process value (PV) can be optionally set from Red, Orange and Green as compare with Setting value (SV).

- Compact size
  - Depth is compact size, TTM-204 is only 55mm, and TTM-205, 207 and 209 are also only 65mm.
- •Loader communication function The best for the setup work of a parameter Cable: Option (sold separately) Software: Free option ---- It can download from our web site
- Abundant output type Relay contact, SSR-driving, Open collector, Voltage (5 types) and Electric current
- •Substantial option function ①CT input (Max. of 2 points) ②Event input (Max. of 4 points) ③Event output (Max. of 7 points. However, when 7 points are used, you can not use the control output.)
- •External standards
- We have acquired "CE", "UL" and cUL.
- Protection structure (Available only for TTM-204)
   Corresponding to "IP66"

- •Valve position proportionality control
- The function carries out valve position proportionality control without feedback resistance.
- Two choices of case colors (Available only for TTM-204) "Black" or "Gray" choice is possible to preference
- Blind function
- The system can be configured so that only specific, selected parameters are displayed from set of parameters.
- Simple timer function (independent three points)
   The order of "After the defined time period passes, the control starts or stops" can be controlled by one unit.
   Also use by the timer independent is possible. (Event output ON/OFF)
- •Priority screen

Without showing a parameter screen, a display and a setup can be performed by indicating a necessary parameter screen on the operation mode screen. (Maximum of 16 screens)

- Digital PV filter
  - Corresponding to the sudden change of input value, it can apply the filter with the software
- Manual control

A manual output function enables application of various instrumentation systems

Communication function (RS485: An exclusive protocol / MODBUS) The range extends up to the distance of 500m, and can connect up to 31 units concurrently.

With one host computer, it can remote consolidate watching "The collection of the data" and "Change of each setting value" at the place where it is far.

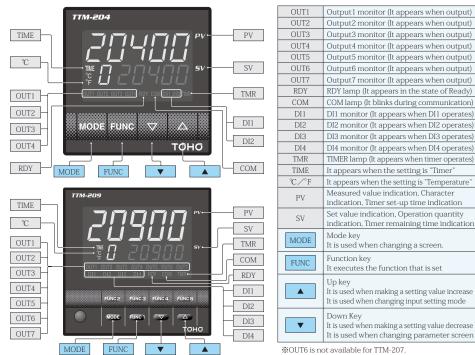
•Soft-start function

When the power supply is turned on, limitation can be put on manipulated value during specific time in PID control.

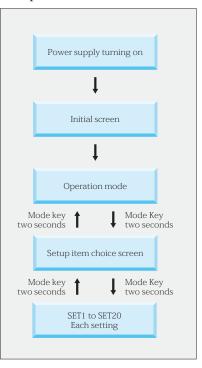
- •Delay timer (Available only ON/OFF control) It is possible to make the action of control output (Main or auxiliary) delay during specific time (setting).
- •Auto/Manual control change

It is possible to change Auto/Manual control and also manipulated value from front panel keys by using FUNC function.

## Front Panel



## ■Operation flow





# ■Standard specification

Input type									
	Thermocouple		L, WRe5-26, PR40-20, PI	.II (Input resistance 1M	Ω)				
	RTD								
	Electric current / voltage				/DC, 0 to 10VDC, 0 to 10mVDC (Input resistance 1MΩ or more)				
Indication	PV/Character indication		LED back light, luminou	s colors are Red, Orang	re and Green)				
( LCD Indication)		TTM-204/205 5	digits, height 10mm						
			digits, height 13mm						
		TTM-209 5 digits, height 20mm							
	SV/Setting indication	LCD indication (with I	LED back light, luminou	s color is Red)					
		TTM-204/205 5	digits, height 8mm						
		TTM-207 5	digits, height 8mm						
		TTM-209 5							
	Auxiliary indication part	LCD indication (with I	LED back light, luminou	s color is Green)					
		TTM-204/205 1	digit, height 8mm						
		TTM-207 1	digit, height 8mm						
		TTM-209 1	digit, height 10mm						
	Each functional indication	Red (OUT1, OUT2, OU	T3, OUT4, OUT5, OUT6,	OUT7, DRY, COM, DI1,	DI2, DI3, DI4, TMR)				
	PV color auto-change	Luminous color	Red, Orange and Gre	en					
		Luminous color	Temperature input	0.0 to 999.9 or 0 to 9	99 (°C )				
		change range	Analogue input	0 to 9999 (digit)					
Control	PID	Proportional band (P	1)	0.1 to 200.0% of set	limiter span				
	(With auto tuning)	Proportional band sid	le of Output 2 (P2)		Per main control proportional band)				
	(With self tuning)	Integration time (I)			ith "0" integral action OFF)				
		Differentiation time (	D)		ith "0" derivative control action OFF)				
		Proportion cycle (T1,		0.1 to 120.0 seconds					
		Dead band (DB)		Temperature input	-999.9 to 999.9 or -999 to 999 (°C )				
		Dead band (DD)		Analog input	-9999 to 9999 (digits) {The decimal point position is the specified position.}				
	ON/OPE	Countries Loop and Ministery (C1	1 (2)	0 1					
	ON/OFF	Control sensitivity (C1	1, 02)	Temperature input	0.0 to 999.9 or 0 to 999 (°C )				
	Output Lando Officia	Deside 1	*!	Analog input	0 to 9999 (digits) {The decimal point position is the specified position.}				
	Output 1 and 2 Off point	Position selection set	ung	SV unit setting High					
		Positional setting		Temperature input	-999.9 to 999.9 or -999 to 999 (°C )				
				Analog input	-9999 to 9999 (digits) {The decimal point position is a specified position.}				
Control output	Relay contact		e load) 1a contact poin	t Minimum load 5VDC	100mA				
	SSR-driving voltage		stance 600 $\Omega$ or more)						
	Open collector	24VDC 100mA							
	Current / voltage	4 to 20mADC (Load re	esistance $600 \Omega$ or less)						
	Voltage	0 to 1VDC (Load resist	tance 500KΩ or more).	0 to 5VDC (Load resista	ance 1K $\Omega$ or more), 1 to 5VDC (Load resistance 1K $\Omega$ or more)				
			stance 1KΩ or more), 0						
Sampling cycle		0.2 seconds			······································				
Setting and instruction	Thermocouple	K, J, T, E, R, S, B, N		Larger one ± (0.3%+	ldigit) of the instruction value or ±2℃ (23℃±10℃)				
accuracy	mennocoupie	R, J, I, L, R, J, D, N		However100 to 0°C	C is $\pm 3^{\circ}$ C, and -200 to -100°C is $\pm 4^{\circ}$ C. As for 400°C or less of B thermocouple there				
(In ambient temperature 23°C				is no stipulation					
±10 degree)		U, L		Larger one $\pm$ (0.3%+1 digit) of the instruction value or $\pm 4^{\circ}$ C (23°C $\pm 10^{\circ}$ C) Less than 0°C is $\pm 6^{\circ}$ C.					
		WRe5-26		Larger one $\pm (0.6\% + 1 \text{ digit})$ of the instruction value or $\pm 4^{\circ}\mathbb{C}$ ( $23^{\circ}\mathbb{C} \pm 10^{\circ}\mathbb{C}$ )					
		PR40-20		$\pm 9.4^{\circ}\text{C} \pm 1 \text{ digit.}$ There is no precision stipulation under $800^{\circ}\text{C}$					
		PLI		Larger one $\pm$ (0.3%+1 digit) of the instruction value or $\pm 2^{\circ}$ C					
	RTD	Pt100, JPt100			ldigit) of the instruction value of $\pm 2.0^{\circ}$ (23°C $\pm 10^{\circ}$ C)				
	Current/voltage	0 to 1VDC, 0 to 5VDC		$\pm 0.3\% \pm 1 \text{ digit of set limiter span } (23^\circ \text{C} \pm 10^\circ \text{C})$					
	current/voltage		2 4 to 20 ADC	±0.5%±1digit of se	$(11111101 \text{ span}(250 \pm 100))$				
		1 to 5VDC, 0 to 10VDC, 4 to 20mADC							
		0 to 10mVDC		$\pm 0.5\% \pm 1$ digit of se	t limiter span (23°C±10°C )				
Memory element		EEPROM							
Input power supply		100 to 240VAC, 50/60	Hz, 24VAC/DC 50/ 60Hz	2					
Weight			205:210g TTM-207:2						
Power consumption		TTM-204 less than 10	VA (100 to 240VAC), les	s than 4W (24VAC/DC),	TTM-205/207/209 less than 11VA (100 to 240VAC), less than 5W (24VACDC)				
Accessories		Simple instruction ma	anual and Attachment (	A handling description	is sold separately.)				
1000300103									
Standard Range of surrounding		23℃±10℃,45 to 75	% RH						
Standard Range of surrounding (Compensating range such as pr	recision)	23°C±10°C, 45 to 75							
Standard Range of surrounding	recision)	23℃±10℃,45 to 75 0 to 50℃,20 to 90%	RH (Avoid dewiness)						
Standard Range of surrounding (Compensating range such as pr	ecision) berature humidity	23℃±10℃,45 to 75 0 to 50℃,20 to 90%		to 95% RH (Avoid dew	iness)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp	ecision) berature humidity	$23^{\circ}C \pm 10^{\circ}C$ , $45 \text{ to } 75$ 0 to $50^{\circ}C$ , 20 to $90\%$	RH (Avoid dewiness) winess and freezing), 5	to 95% RH (Avoid dew Digital output	iness) MLL1 to 100.0 (%), MLL2 to 100.0 (%)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) perature humidity ings temperature humidity	23°C±10°C, 45 to 75 0 to 50°C, 20 to 90% -20 to 70°C (Avoid de	RH (Avoid dewiness) winess and freezing), 5						
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	recision) berature humidity ings temperature humidity Manipulated variable limiter	23°C±10°C, 45 to 75 0 to 50°C, 20 to 90% -20 to 70°C (Avoid de	RH (Avoid dewiness) winess and freezing), 5 LH2)	Digital output	MLL1 to 100.0 (%), MLL2 to 100.0 (%)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	recision) berature humidity ings temperature humidity Manipulated variable limiter	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90% -20 to 70°C (Avoid de Upper limit (MLH1, M	RH (Avoid dewiness) winess and freezing), 5 LH2)	Digital output Analogue output	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) perature humidity ings temperature humidity Manipulated variable limiter (MLH 1, MLL1, MLH2, MLL2)	23℃±10℃,45 to 75 0 to 50℃,20 to 90% -20 to 70℃ (Avoid de Upper limit (MLH1, M Lower limit (MLL1, M	RH (Avoid dewiness) winess and freezing), 5 LH2) LL2)	Digital output Analogue output Digital output	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	recision) berature humidity ings temperature humidity Manipulated variable limiter	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90% -20 to 70°C (Avoid de Upper limit (MLH1, M	RH (Avoid dewiness) winess and freezing), 5 LH2) LL2)	Digital output Analogue output Digital output	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) perature humidity ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of	23℃±10℃,45 to 75 0 to 50℃,20 to 90% -20 to 70℃ (Avoid de Upper limit (MLH1, M Lower limit (MLL1, M	RH (Avoid dewiness) winess and freezing), 5 LH2) LL2)	Digital output Analogue output Digital output	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) perature humidity ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter	23℃±10℃,45 to 75 0 to 50℃,20 to 90% -20 to 70℃ (Avoid de Upper limit (MLH1, M Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func	RH (Avoid dewiness) winess and freezing). 5 LH2) LL2) :tion OFF by 0.0%)	Digital output Analogue output Digital output	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) perature humidity ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90% -20 to 70°C (Avoid de Upper limit (MLH1, M Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Analog output	RH (Avoid dewiness) winess and freezing), 5 LH2) LL2) :tion OFF by 0.0%) 0.0 to 100.0 (%)	Digital output Analogue output Digital output	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) berature humidity ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90% -20 to 70°C (Avoid de Upper limit (MLH1, M Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output	RH (Avoid dewiness) winess and freezing), 5 LH2) LL2) :tion OFF by 0.0%) 0.0 to 100.0 (%)	Digital output Analogue output Digital output Analogue output Temperature input	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (°C)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) perature humidity ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting	23°C±10°C, 45 to 75 0 to 50°C, 20 to 90% -20 to 70°C (Avoid de Upper limit (MLH1, M Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH)	RH (Avoid dewiness) winess and freezing), 5 LH2) LL2) :tion OFF by 0.0%) 0.0 to 100.0 (%)	Digital output Analogue output Digital output Analogue output Temperature input Analogue input	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (°C) (SLL + 5.0) to SV setting range upper limit (digit)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) perature humidity ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90% -20 to 70°C (Avoid de Upper limit (MLH1, M Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Analog output	RH (Avoid dewiness) winess and freezing), 5 LH2) LL2) :tion OFF by 0.0%) 0.0 to 100.0 (%)	Digital output Analogue output Digital output Analogue output Temperature input Analogue input Temperature input	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (C) (SLL + 5.0) to SV setting range upper limit, (digit) SV setting range lower limit to (SLH - 5), SV setting range lower limit to (SLH - 5) (C)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) berature humidity ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH)	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90% -20 to 70°C (Avoid de Upper limit (MLL1, MI Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH) Lower limit (SLL)	RH (Avoid dewiness) winess and freezing), 5 LH2) tL2 ttion OFF by 0.0%) 0.0 to 100.0 (%) -10.0 to 110.0 (%)	Digital output Analogue output Digital output Analogue output Temperature input Analogue input Analogue input	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (°C) (SLL + 5.0) to SV setting range upper limit, (digit) SV setting range lower limit to (SLH - 50, SV setting range lower limit to (SLH - 5) (°C) SV setting range lower limit to (SLH - 50) (digit)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) erature humidity ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH) Control mode (MD)	23°C±10°C, 45 to 75 0 to 50°C, 20 to 90% -20 to 70°C (Avoid de Upper limit (MLL1, MI Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control	RH (Avoid dewiness) winess and freezing), 5 LH2) tL2 ttion OFF by 0.0%) 0.0 to 100.0 (%) -10.0 to 110.0 (%)	Digital output Analogue output Digital output Analogue output Temperature input Analogue input Temperature input Analogue input trol, timer1 operation,	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (°C) (SLL + 5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH - 50), SV setting range lower limit to (SLH - 5) (°C) SV setting range lower limit to (SLH - 50) (digit) timer2 operation, and timer3 operation				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) berature humidity ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH)	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90% -20 to 70°C (Avoid de Upper limit (MLL1, MI Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH) Lower limit (SLL)	RH (Avoid dewiness) winess and freezing), 5 LH2) tL2 ttion OFF by 0.0%) 0.0 to 100.0 (%) -10.0 to 110.0 (%)	Digital output Analogue output Digital output Analogue output Temperature input Analogue input Temperature input Analogue input Tot, timer I operation, Type A (Normal PID)	MLL1 to 100.0 (%), MLL2 to 100.0 (%)           MLL1 to 110.0 (%), MLL2 to 110.0 (%)           0.0 to MLH1 (%), 0.0 to MLH2 (%)           -10.0 to MLH1 (%), -10.0 to MLH2 (%)           (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (°C)           (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (°C)           (SL + 5.0) to SV setting range upper limit (digit)           SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5) (°C)           SV setting range lower limit to (SLH - 5.0) (digit)           timer2 operation, and timer3 operation           control type)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) erature humidity ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH) Control mode (MD)	23°C±10°C, 45 to 75 0 to 50°C, 20 to 90% -20 to 70°C (Avoid de Upper limit (MLL1, MI Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control	RH (Avoid dewiness) winess and freezing), 5 LH2) tL2 ttion OFF by 0.0%) 0.0 to 100.0 (%) -10.0 to 110.0 (%)	Digital output Analogue output Digital output Analogue output Temperature input Analogue input Temperature input Analogue input Type A (Normal PID Type B (Over-shoot p	MLL1 to 100.0 (%), MLL2 to 100.0 (%)           MLL1 to 110.0 (%), MLL2 to 110.0 (%)           0.0 to MLH1 (%), 0.0 to MLH2 (%)           -10.0 to MLH1 (%), -10.0 to MLH2 (%)           (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (C)           (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (Gigit)           SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5.0) (C)           SV setting range lower limit to (SLH - 5.0) (digit)           timer2 operation, and timer3 operation control type)           rotection type)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) erature humidity ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH) Control mode (MD)	23°C±10°C, 45 to 75 0 to 50°C, 20 to 90% -20 to 70°C (Avoid de Upper limit (MLH1, M Lower limit (MLL1, Ml 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control PID type	RH (Avoid dewiness) winess and freezing), 5 LH2) tL2 ttion OFF by 0.0%) 0.0 to 100.0 (%) -10.0 to 110.0 (%)	Digital output Analogue output Digital output Analogue output Analogue input Temperature input Analogue input trol, timer I operation, Type B (Normal PID Type B (Ver-shoot Type C (External dist	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (°C) (SLL + 5.0) to SV setting range upper limit, (digit) SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5) (°C) SV setting range lower limit to (SLH - 5.0) (digit) timer2 operation, and timer3 operation control type) urbance protection type)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) erature humidity ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH) Control mode (MD)	23°C±10°C, 45 to 75 0 to 50°C, 20 to 90% -20 to 70°C (Avoid de Upper limit (MLL1, MI Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH) Lower limit (SLL) Control stop, control	RH (Avoid dewiness) winess and freezing), 5 LH2) tL2 ttion OFF by 0.0%) 0.0 to 100.0 (%) -10.0 to 110.0 (%)	Digital output Analogue output Digital output Analogue output Temperature input Analogue input Temperature input Analogue input trol, timer1 operation, Type A (Normal PID) Type B (Over-shoot protectic Over-shoot protectic	MLL1 to 100.0 (%), MLL2 to 100.0 (%)           MLL1 to 110.0 (%), MLL2 to 110.0 (%)           0.0 to MLH1 (%), 0.0 to MLH2 (%)           -10.0 to MLH1 (%), -10.0 to MLH2 (%)           (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (°C)           (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (°C)           SV setting range lower limit to (SLH - 50, SV setting range lower limit to (SLH - 50) (C)           SV setting range lower limit to (SLH - 50) (digit)           timer2 operation, and timer3 operation           control type)           protection type)           ordenate           wirbance protection type)           on Weak				
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Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) verature humidity Ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH) Control mode (MD) Control types (CNT)	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90%. -20 to 70°C (Avoid de Upper limit (MLH1, M Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Upper limit (SLH) Lower limit (SLH) Lower limit (SLH) Control stop, control PID type Type B mode Normal reverse action Tuning type setting 0.0 to 1000.0 (%) Temperature input	RH (Avoid dewiness) winess and freezing). 5 LH2) LL2) ction OFF by 0.0%) -10.0 to 100.0 (%) -10.0 to 110.0 (%) beginning, manual con	Digital output Analogue output Digital output Analogue output Analogue output Temperature input Analogue input Temperature input Analogue input Tol, timer I operation, Type B (Over-shoot protecti Over-shoot	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (C) (SL + 5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5) (C) SV setting range lower limit to (SLH - 5.0) (digit) timer2 operation, and timer3 operation control type) urbance protection type) m Weak on Middle on Strong Hain PID/position proportionality control) ig (Main PID/auxiliary PID) (Main PID/auxiliary PID) tuning (Main PID/auxiliary PID)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) berature humidity Ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH) Control mode (MD) Control types (CNT) Control types (CNT) Output gain setting (MV1G, MV2G) PV correction, 0 point setting (PVS)	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90% -20 to 70°C (Avoid de Upper limit (ML11, Ml Lower limit (ML11, Ml 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH) Lower limit (SLH) Lower limit (SLL) Control stop, control PID type Type B mode Normal reverse action Tuning type setting 0.0 to 1000.0 (%) Temperature input Analog input	RH (Avoid dewiness) winess and freezing). 5 LH2) LL2) O to 100.0 (%) -10.0 to 110.0 (%) beginning, manual con n setting	Digital output Analogue output Digital output Analogue output Analogue output Temperature input Temperature input Analogue input Temperature input Analogue input Type B (Over-shoot protectic Over-shoot protectic Over-shoot protectic Over-shoot protectic Reverse action Normal action Main auto-tuning (M Main self-tuning (M Auxiliary self-tuning Main/auxiliary auto-	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (C) (SL + 5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5) (C) SV setting range lower limit to (SLH - 5.0) (digit) timer2 operation, and timer3 operation control type) urbance protection type) m Weak on Middle on Strong Hain PID/position proportionality control) ig (Main PID/auxiliary PID) (Main PID/auxiliary PID) tuning (Main PID/auxiliary PID)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) perature humidity Imgs temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH) Control mode (MD) Control types (CNT) Control types (CNT) Output gain setting MV1G, MV2G) PV correction, 0 point setting (PVG)	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90% -20 to 70°C (Avoid de Upper limit (MLL1, MI Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH) Lower limit (SLH) Lower limit (SLH) Control stop, control PID type Type B mode Normal reverse action Tuning type setting 0.0 to 1000.0 (%) Temperature input Analog input 0.500 to 2.000 (times)	RH (Avoid dewiness) winess and freezing). 5 LH2) LL2) O to 100.0 (%) -10.0 to 110.0 (%) beginning, manual con n setting	Digital output Analogue output Digital output Analogue output Analogue output Temperature input Analogue input Temperature input Analogue input Tol, timer I operation, Type B (Over-shoot protecti Over-shoot	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (C) (SL + 5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5) (C) SV setting range lower limit to (SLH - 5.0) (digit) timer2 operation, and timer3 operation control type) urbance protection type) m Weak on Middle on Strong Hain PID/position proportionality control) ig (Main PID/auxiliary PID) (Main PID/auxiliary PID) tuning (Main PID/auxiliary PID)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) perature humidity Ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH) Control mode (MD) Control types (CNT) Output gain setting MV1G, MV2G) PV correction, 0 point setting (PVG) PV input filter (PD)	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90%. -20 to 70°C (Avoid de Upper limit (MLH1, M Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Upper limit (SLH) Lower limit (SLH) Lower limit (SLH) Lower limit (SLH) Control stop, control PID type Type B mode Normal reverse action Tuning type setting 0.0 to 1000.0 (%) Temperature input Analog input 0.0 to 99.9 (seconds)	RH (Avoid dewiness) winess and freezing), 5 LH2) LL2 tion OFF by 0.0% 0.0 to 100.0 (%) -10.0 to 110.0 (%) beginning, manual con a setting	Digital output Analogue output Digital output Analogue output Analogue output Temperature input Temperature input Analogue input Temperature input Analogue input Type A (Normal PID Type B (Over-shoot protectic Over-shoot protectic Over-shoot protectic Over-shoot protectic Over-shoot protectic Over-shoot protectic Normal action Main auto-tuning (M Auxiliary self-tuning	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (C) (SL + 5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5) (C) SV setting range lower limit to (SLH - 5.0) (digit) timer2 operation, and timer3 operation control type) urbance protection type) m Weak on Middle on Strong Hain PID/position proportionality control) ig (Main PID/auxiliary PID) (Main PID/auxiliary PID) tuning (Main PID/auxiliary PID)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) berature humidity Ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH) Control mode (MD) Control types (CNT) Control types (CNT) Output gain setting (MV1G, MV2G) PV correction, opint setting (PVG) PV input filter (PD) Andt reset windup	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90%. -20 to 70°C (Avoid de Upper limit (MLH1, M Lower limit (MLL1, ML 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH) Lower limit (SLH) Lower limit (SLL) Control stop, control PID type Type B mode Normal reverse action Tuning type setting 0.0 to 1000.0 (%) Temperature input Analog input 0.500 to 2.000 (times) 0.0 to 1100 (%) (Func	RH (Avoid dewiness) winess and freezing). 5 LH2) LL2) O to 100.0 %) -10.0 to 110.0 %) beginning, manual con n setting tition OFF by 110.0% set	Digital output Analogue output Digital output Analogue output Analogue output Temperature input Analogue input Temperature input Analogue input Temperature input Topue a (Over-shoot protectic Over-shoot protectic Over-shoot protectic Over-shoot protectic Over-shoot protectic Reverse action Main auto-tuning (M Main self-tuning (M Main self-tuning (M Main self-tuning (M Main self-tuning (M Auxiliary self-tuning Main/auxiliary auto- -999.9 to 999.9 (C ) -9999 to 999.9 (C )	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (C) (SL + 5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5) (C) SV setting range lower limit to (SLH - 5.0) (digit) timer2 operation, and timer3 operation control type) urbance protection type) m Weak on Middle on Strong Hain PID/position proportionality control) ig (Main PID/auxiliary PID) (Main PID/auxiliary PID) tuning (Main PID/auxiliary PID)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) berature humidity Ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH) Control mode (MD) Control mode (MD) Control types (CNT) Control types (CNT) Output gain setting (MV1G, MV2G) PV correction, 0 point setting (PVG) PV iorrection, gain setting (PVG) PV ioput filter (PD) Anti reset windup Manual reset (PBB)	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90% -20 to 70°C (Avoid de Upper limit (ML11, Ml Lower limit (ML11, Ml 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH) Lower limit (SLH) Lower limit (SLL) Control stop, control PID type Type B mode Normal reverse action Tuning type setting 0.0 to 1000.0 (%) (Func 0.0 to 1000.0 (%) (Func	RH (Avoid dewiness) winess and freezing). 5 LH2) LL2) tition OFF by 0.0%) 0.0 to 100.0 (%) -10.0 to 110.0 (%) beginning, manual con n setting tition OFF by 110.0% set 0. to 100.0 (%) if there i	Digital output Analogue output Digital output Analogue output Analogue output Temperature input Analogue input Temperature input Analogue input Temperature input Analogue input trol, timer I operation, Type A (Normal PID- Type B (Over-shoot protectic Over-shoot protectic Auxiliary auto-tuning (M Ain auto-tuning (M Ain auxiliary auto-tuning Main/auxiliary auto- -999.9 to 999.9 (°C) - -999.9 to 999.9 (digit)	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (C) (SL + 5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5) (C) SV setting range lower limit to (SLH - 5.0) (digit) timer2 operation, and timer3 operation control type) urbance protection type) m Weak on Middle on Strong Hain PID/position proportionality control) ig (Main PID/auxiliary PID) (Main PID/auxiliary PID) tuning (Main PID/auxiliary PID)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) berature humidity Ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH) Control mode (MD) Control types (CNT) Control types (CNT) Output gain setting (MV1G, MV2G) PV correction, opint setting (PVG) PV input filter (PD) Andt reset windup	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90% -20 to 70°C (Avoid de Upper limit (MLL1, MI Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH) Lower limit (SLH) Lower limit (SLH) Control stop, control PID type Type B mode Normal reverse action Tuning type setting 0.0 to 1000.0 (%) Temperature input Analog input 0.500 to 2.000 (times) 0.0 to 1000.0 (%) (Func 0.0 to 1000.0 (%) (Func Main control loop abr	RH (Avoid dewiness) winess and freezing). 5 LH2) LL2 tion OFF by 0.0%) 0.0 to 100.0 (%) -10.0 to 110.0 (%) beginning, manual con n setting tion OFF by 110.0% set 0. to 100.0 (%) if there in normal time setting	Digital output Analogue output Digital output Analogue output Analogue output Temperature input Temperature input Tamperature input Analogue input Temperature input Analogue input Type R (Normal PID Type R (Normal PID Normal action Main auto-tuning (Nama Auxiliary auto-tuning Main/auxiliary auto- -999.9 to 999.9 (C) -999.9 to 999.9 (C) -999.9 to 999.9 (C) 10 to 9999 (seconds)	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (C) (SL + 5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5) (C) SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5) (C) SV setting range lower limit to (SLH - 5.0) (digit) timer2 operation, and timer3 operation control type) urbance protection type] n Weak on Middle on Strong Iain PID/position proportionality control) ig (Main PID/auxiliary PID) (Main PID/auxiliary PID) tuning (Main PID/auxiliary PID)				
Standard Range of surrounding (Compensating range such as pr Range of use surroundings temp Range of preservation surroundi	ecision) berature humidity Ings temperature humidity Manipulated variable limiter (MLH1, MLL1, MLH2, MLL2) Upper limit lower limit setting of manipulated variable change limiter Abnormal time manipulated variable setting Setting limiter (SLL, SLH) Control mode (MD) Control mode (MD) Control types (CNT) Control types (CNT) Output gain setting (MV1G, MV2G) PV correction, 0 point setting (PVG) PV iorrection, gain setting (PVG) PV ioput filter (PD) Anti reset windup Manual reset (PBB)	23°C ± 10°C , 45 to 75 0 to 50°C , 20 to 90% -20 to 70°C (Avoid de Upper limit (MLL1, MI Lower limit (MLL1, MI 0.0 to 549.9 (%) (Func Digital output Analog output Upper limit (SLH) Lower limit (SLH) Lower limit (SLH) Control stop, control PID type Type B mode Normal reverse action Tuning type setting 0.0 to 1000.0 (%) Temperature input Analog input 0.500 to 2.000 (times) 0.0 to 1000.0 (%) (Func 0.0 to 1000.0 (%) (Func Main control loop abr	RH (Avoid dewiness) winess and freezing). 5 LH2) LL2) tition OFF by 0.0%) 0.0 to 100.0 (%) -10.0 to 110.0 (%) beginning, manual con n setting tition OFF by 110.0% set 0. to 100.0 (%) if there i	Digital output Analogue output Digital output Analogue output Analogue output Temperature input Temperature input Tamperature input Analogue input Temperature input Analogue input Type R (Normal PID Type R (Normal PID Normal action Main auto-tuning (Nama Auxiliary auto-tuning Main/auxiliary auto- -999.9 to 999.9 (C) -999.9 to 999.9 (C) -999.9 to 999.9 (C) 10 to 9999 (seconds)	MLL1 to 100.0 (%), MLL2 to 100.0 (%) MLL1 to 110.0 (%), MLL2 to 110.0 (%) 0.0 to MLH1 (%), 0.0 to MLH2 (%) -10.0 to MLH1 (%), -10.0 to MLH2 (%) (SLL + 5.0) to SV setting range upper limit, (SLL + 5) to SV setting range upper limit (°C) (SL + 5.0) to SV setting range upper limit (digit) SV setting range lower limit to (SLH - 5.0), SV setting range lower limit to (SLH - 5) (°C) SV setting range lower limit to (SLH - 5.0) (digit) timer2 operation, and timer3 operation control type) urbance protection type] or Meak on Middle on Strong Hain PID/position proportionality control) in PID/position proportionality control) (Main PID/auxiliary PID) (Main PID/auxiliary PID) tuning (Main PID/auxiliary PID)				

# ■ Standard specification

Function	Timer driving mode (TMF)	Three points. 0 minute and 00 second to 99 Timer repetition frequency: 0 to 99 times ( Accuracy: ±(1.5% + 0.5 seconds) of setting	With 0 unlimited freque	ids. 0 hour and 00 minute to 99 hours and 59 minutes. ency)					
		Function: Auto start, Manual start, Event st	art, SV start, DI start						
	Delay timer (FDT)	0 to 99 (minutes) Main/auxiliary common							
	Decimal point movement (DP)	Indication below decimal point. Yes/No							
	Manual control	Manual control is possible. (Balance-less / Bump-less)							
	RUN/READY	Switching of RUN/READY is possible.	Switching of RUN/READY is possible.						
	Blind function	An optional parameter screen can be set u	An optional parameter screen can be set up in the non-indication.						
	Auto tuning coefficient (ATG)	0.1 to 10.0 times							
	Auto tuning sensitivity (ATC)	Temperature input	0.0 to 999.9 or 0 to 99	99 (°C )					
		Analog input	0 to 9999 (digits)						
	Function key	A function key can be chosen from "Figure movement", "MD/ready", "AT start/stop", "Timer start/reset", "Reverse screen turning", "ENT", "Bank							
		and "Auto/manual change". Settlement of push time (0 to 5 seconds)							
	Priority screen	An optional parameter screen can be indicated in the operation mode. (Maximum of 16 points)							
	Lock function (LOC)	Four modes (OFF, ALL Lock, Operation mod	Four modes (OFF, ALL Lock, Operation mode lock, and lock except operation mode)						
	Self-diagnostic function	EEPROM data check (Err0), A/D converter a	ction check (Err1), auto	-tuning check (Err2), watch-dog timer equipped					
	Ramp function	Action	When modify SV, set	up the SV variation per minute					
		Setting range	Temperature input	0.0 to 999.9 (Ramp function turns OFF by 0.0)					
			Analog input	ากการการการการการการการการการการการการกา					
		Setting unit	Temperature input	0.1°C/minute					
			Analog input	0.1 digit/minute					
	Valve function	Motor stroke time	0.1 to 999.9 (seconds	)					
		Motor drive dead band	0.0 to 100.0 (seconds)						
	Initialization mode	Password setup, blind screen one time call Since a password is required for this mode	Password setup, blind screen one time call setup, setting value backup and set value initialization Since a password is required for this mode when making a setting change, please be sure to keep the password.						
	Bank setting	Setting the parameter of set 1 to 17 (A max	timum of 16 points)						
	Soft-start (Main control)	Output setting	MLL1 to MLH1 (%)						
		Time setting	00:00 to 99:59 (minutes). Function OFF by 00:00 (minutes)						

# ■Option specification

		050040.14 (	1 10 1							
Auxiliary output (2 points)	Relay contact		ce load) 1a contact point							
(Common	Open collector	24VDC 100mA								
Terminal)	Setting range (Upper and Lower	Temperature input	−1999.9 to 2999.9、−19999 to 29999(°C)							
	limit)	Analog input	-19999 to 29999( digit)							
	Sensitivity	Temperature input 0.0 to 999.9, 0 to 999.9 °C								
		Analog input	0 to 9999( digit)							
	Delay timer	0 to 9999 (seconds)	to 9999 (seconds)							
DI input (Max. 4 points)	Function	Forward action swite	ch (At the time of contact point closing is Forwar							
		Auto tuning STOP/S	TART (At the time of contact point closing is Auto	o tuning Start), Timer STOP/START (At the time of contact point closing START)						
	Input specification	No voltage contact p	point. Active switching is possible at the time of t	he input.						
	Minimum input time	200mS								
	When ON electric current	Maximum 10mADC								
	When OFF electric current	Maximum 6VDC								
	Terminal permission resistance	When ON: Maximun	n 333Ω, When OFF: Minimum 500KΩ							
CT input	Measurement electric current range	0.0 to 50.0A								
(2 points)	Setting electric current range	0.0 to 30.0A (Setting	resolution 0.1A). However, the function is turnir	ng off at 0.0.						
	Setting accuracy		5% (0.14 of less is outside accuracy)							
	Wire break detection	ON time of control o	<i></i>							
	Welding detection		output above 300mS							
Communication	Treiding detection	Communication	suparabore ocomo	Loader communication						
communication	Communication standard	RS-485 (1:31)		TTL (1:1)						
	Communication terminal Protocol	Terminal stand		Loader communication private terminal						
		· · ·	tocol/MODBUS (RTU)/MODBUS (ASCII)	TOHO exclusive protocol/MODBUS (RTU)/MODBUS (ASCII)						
	Direction of information	Half duplex		Half duplex						
	Synchronous system	Asynchronous		Asynchronous						
	Transmission code	ASCII		ASCII						
	Interface	RS-485 (two lines)		TTIL level						
	Transmission speed	2400, 4800, 9600, 19	200, 38400bps	2400, 4800, 9600, 19200, 38400bps						
	Communication distance	500m								
	Response delay time	0 to 250mS		0 to 250mS						
	Communication switch	Writing is impossible	e/Writing is possible/Simultaneous temperature	rise master/Simultaneous temperature rise slave.						
	Character	Start bit: 1 bit fixatio	n	Start bit: 1 bit fixation						
		Stop bit: 1/2 bit		Stop bit: 1/2 bit						
		Data length: 7/8 bit * MODBUS: In case of In case of RTU 8 b	f ASCII 7 bits fixation its fixation	Data length: 7/8 bit * MODBUS: In case of RTU 7 bits fixation In case of RTU 8 bits fixation						
		Parity: No/Even num		Parity: No/Even number/Odd number						
		BCC check: No/Yes	BCC Check is invalid	BCC check: No/Yes * In case of MODBUS BCC Check is invalid						
		Address: 1 to 99 stat		Address: 1 to 99 stations * In case of MODBUS 1 to 247 stations						
Transmission output	Functional setting			ipulated variable) output, MV2 (Secondary manipulated variable) output. Reciprocal change						
		Temperature input	Scaling low limit to 2999.9 (°C ), scaling low lim	iit to 2999 (℃ )						
		Analogue input	Scaling low limit to 29999 (digit)							
		Temperature input	-1999.9 to scaling high limit (°C ), -1999 to scali	ing high limit (°C.)						
		Analogue input -19999 to scaling high limit (digit)								



## ■Input and scale range

Thermocouple		Measurement/measurement range	Indication resolution			
K	°C	-200.0 to 1372.0	1℃∕0.1℃			
J	°C	-200.0 to 1200.0	1℃∕0.1℃			
Т	°C	-200.0 to 400.0	1℃∕0.1℃			
Е	°C	-200.0 to 1000.0	1℃∕0.1℃			
R	°C	-50.0 to 1768.0	1°C			
S	°C	-50.0 to 1768.0	1°C			
В	°C	-0.0 to 1800.0	1°C			
N	°C	-200.0 to 1300.0	1℃∕0.1℃			
U	°C	-200.0 to 400.0	1℃∕0.1℃			
L	°C	-200.0 to 900.0	1℃∕0.1℃			
WRe5-26	°C	0.0 to 2300.0	1°C			
PR40-20	°C	0.0 to 1880.0	1℃			
PL II	°C	0.0 to 1390.0	1℃∕0.1℃			

RTD		Measurement/measurement range	Indication resolution	
Pt100(JIS/IEC) °C		-200.0 to 850.0	1℃∕0.1℃	
JPt100(JIS)	°C	-200.0 to 510.0	1℃∕0.1℃	

Current and voltage	Measurement/measurement range	Indication resolution
0 to 1VDC		
0 to 5VDC		
1 to 5VDC	– 19999 to 29999 Indication width is less than	A decimal point position can
0 to 10VDC	20000.	be changed arbitrarily.
0 to 10mVDC		
4 to 20mADC		

## Output connection setting

Main output	
Auxiliary output	
Event output	
RUN output	
RDY output	
Timer1 output	
Timer1 output at on delay	
Timer1 output at off delay	
Timer1 output at on + off delay	
Timer2 output	
Timer2 output at on delay	
Timer2 output at off delay	
Timer2 output at on + off delay	
Timer3 output	
Timer3 output at on delay	
Timer3 output at off delay	
Timer3 output at on + off delay	
Transmission output (When OLIT1 and OLIT2 are analogue output)	

## Timer drive mode

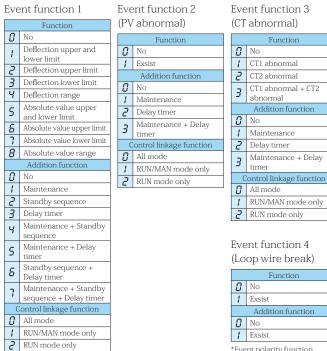
## Start mode

1	Auto start
2	Manual start
3	SV start
4	DI1 start (Possible to set when option is equipped)
5	DI2 start (Possible to set when option is equipped)
6	DI3 start (Possible to set when option is equipped)
7	DI4 start (Possible to set when option is equipped)
8	Event 1 start
9	Event 2 start
10	Event 3 start (Possible to set when option is equipped)
11	Event 4 start (Possible to set when option is equipped)
12	Event 5 start (Possible to set when option is equipped)
13	Event 6 start (Possible to set when option is equipped)
14	Event 7 start (Possible to set when option is equipped)

\*Each Start has ON delay/OFF Delay

ON delay: After time-up control stop or event output OFF OFF delay: After time-up control stop or event output ON

## Point of contact output mode



\*Event polarity function available

## Output functional allotment ( O: Allotment is possible, ×: Allotment impossibility)

Output types	Control	output	Auxiliary output					
Output types	Output1	Output2	Output3	Output4	Output5	Output6	Output7	
Main output (Heating)	0	0	0	0	0	0	0	
Auxiliary output (Cooling)	0	0	0	0	0	0	0	
Transmission	0	0	×	×	×	×	×	
Event output	0	0	0	0	0	0	0	
Timer output	0	0	0	0	0	0	0	

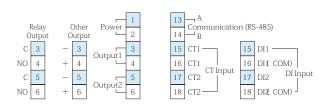
## Terminal explanation

Communication	Please connect the terminal of A and B rightly. (Please use a converter when it is not RE-485)					
Output (Right reverse	Relay point of contact	C: Common, No: Normal open				
change is possible)	SSR driving	Please connect directly with INPUT+ and - by the side of SSR.				
	Transmission, Open collector	Please be connected to polarity of + and - with care				
СТ	Please connect a	a specified current transformer directly. (CTL-6-P-H)				
PV input/ AI input	Thermocouple	Please be connected to polarity of + and - with care				
	Current/ voltage	Please be connected to terminals A, B and b with care				
DI	COM: Common (The polarity can be switched)					
AI input	Please be conne	ected to polarity of + and - with care				

## Wiring

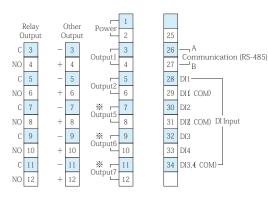
\*Please use less than 6mm width terminal

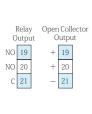
TTM-204



% Output 3 and 4 (Terminals 7 to 9) are possible to select from either relay output or open collector.

## TTM-205、209





Open Collector

Output

9

+ 7

+ 8 7 Output3%

8 Output4%

10

11 Input

12

9 Output3 4% RTD TC/10mV I/V

10 b 10

11 B

А 12 + 12

PV

10

14

15

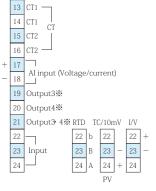
16

Relav Output

NO 7

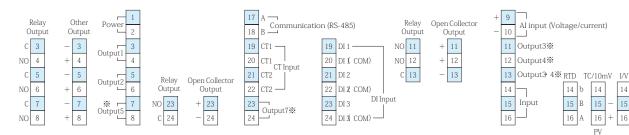
NO 8

С 9



\* Output 3 to 7 (Terminals 19 to 21 and 7 to 12) are possible to select from either relay output or open collector.

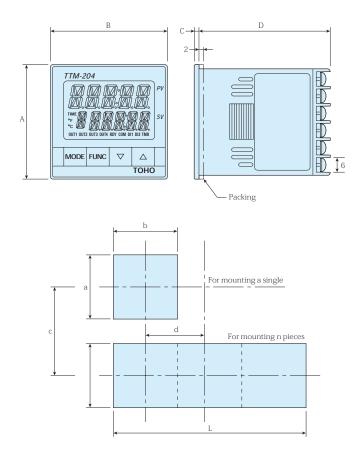
## TTM-207



X Output 3 to 5 and 7 (Terminals 11 to 13, 7 to 8, 23 to 24) are possible to select from either relay output or open collector.

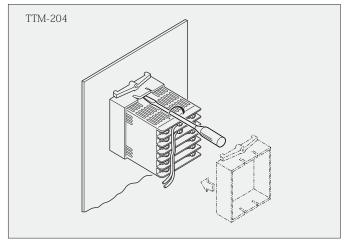


## Dimensions

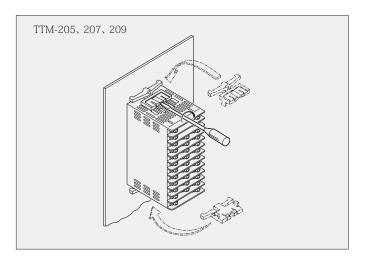


Model		а		b	с	d	А	В	С	D	L	
TTM-204	45	$^{+0.6}_{-0}$	45	$^{+0.6}_{-0}$	60	48	48	48	2	55	(Bxn-3)	$^{+0.6}_{-0}$
TTM-205	92	$^{+0.6}_{-0}$	45	$^{+0.6}_{-0}$	120	48	96	48	2	65	(Bxn-3)	$^{+1}_{-0}$
TTM-207	68	$^{+0.6}_{-0}$	68	$^{+0.6}_{-0}$	90	72	72	72	2	65	(Bxn-3)	$^{+1}_{-0}$
TTM-209	92	$^{+0.6}_{-0}$	92	$^{+0.6}_{-0}$	120	96	96	96	2	65	(Bxn-3)	$^{+1}_{-0}$

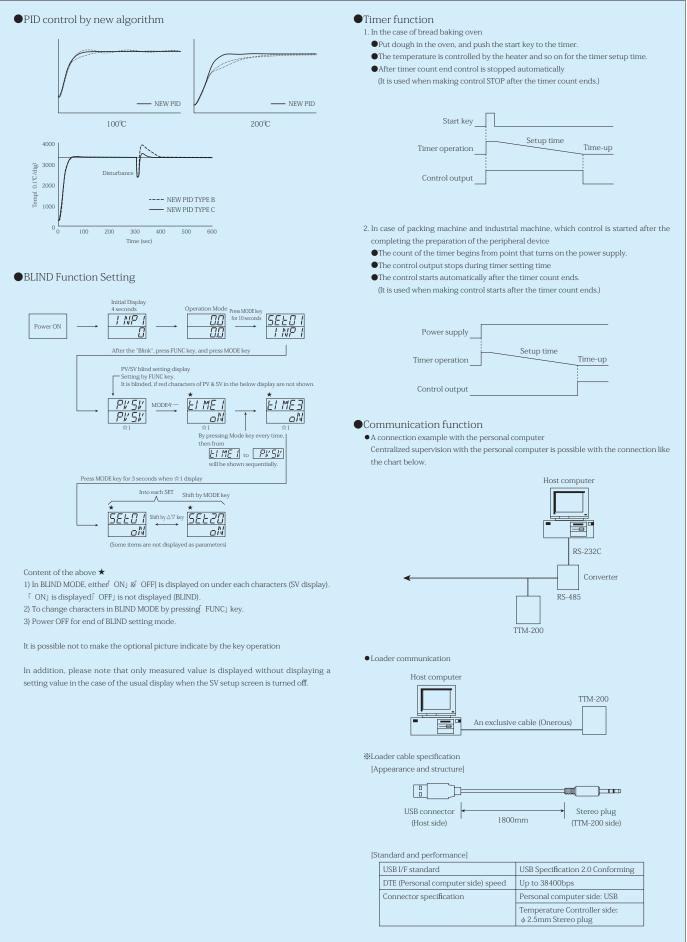
## Panel Installation



 $\ast$  For this panel installation, please be careful sufficiently to avoid any of damage.



## Advanced Feature



[ Model]

TTM-LOADER

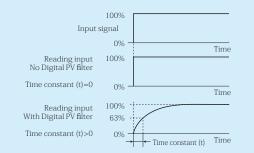


#### • Digital PV filter

It is the function to realize the CR filter effect on the software by performing primary delay operation to the measured value (PV).

The effect of the filter can be set by the time constant.

(Time constant is the time that the PV value reaches up to about 63% when the input changes on the step.)

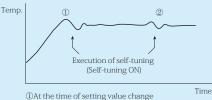


The use of Digital PV filter

1) Removal of high frequency noise --- The influence of a noise when an electric noise joining an input is mitigated.

2) A response can be delayed against the sudden change of the input.

#### Self-tuning PID



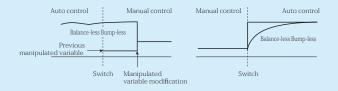
2At the time of the temperature change by disturbance, and at the time of hunching generating

#### Auto (RUN) / Manual function

The auto control and the manual control, they can be switched by the front key. Manual operation is the function that is not concerned with the situation of a deviation, but can set up and output the output for control arbitrarily (manipulation variable).

The system can be operated manually in the time of the system trial run and so on, when to check of final control element (a valve, heater, etc.) of operation is performed, when the sensor breaks down by any chance, or when usual control can't be done.

There is the Balance-less Bump-less function, which holds down sudden change of control output when switching the automatic control and manual control mutually. Furthermore, it stops damage on the peripheral equipment by sudden change and the bad influence to a control system. So, you can operate in comfort.



Balance-less Bump-less

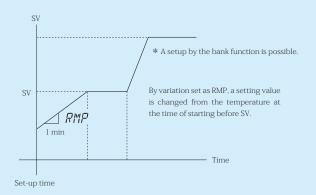
#### Ramp function

The ramp function is a matter of function made to have inclination against the change in SV (Setting value).

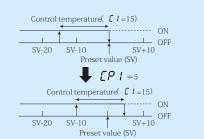
As actual operation, the setting value of a dummy is made to change gradually toward the setting value after changing. Then it controls to the setting value of the dummy. The amount of change for around one minute of SV is set up.

When a rapid change of the control result is not allowed with the characteristic of the control subject, and when the change course (inclination) of the control result becomes important in a control subject, the effect of a ramp function is demonstrated, the effect of the ramp function is demonstrated.

In addition, since only SV is changed, the result expected may not be obtained when it expects great influence to PV (measured value).



●OFF point position movement of ON/OFF control When the OFF point position movement is set to 0, the OFF point is the set value position.



This is when off point position movement is set up with (+5).

Actually specification, there is no description change as above, but move above equal to (+5) as a position of ON/OFF.

Case it made move on negative side, the OFF point moves to opposite side to description above

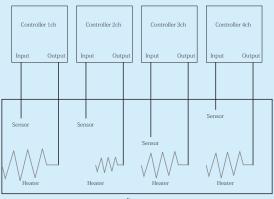
## Heating and cooling



#### •Simultaneous temperature rise function

#### ■Simultaneous temperature rise

- · When simultaneous temperature rise control is exerted by multi-channels using the RS-485 communication function, a master and slave are determined beforehand. This permits reaching the respective goal values at the same time regardless of the characteristic of each channel.
- The channel, in which the time from the start of control to the reach to the goal value is the longest, is specified as a master. The other channels are specified as slaves.
- The simultaneous temperature rise function is started at the start of run (including the power ON time) or a change of setting value, and is ended when the master reaches the goal value.



#### Furna

#### • How to use

- 1. Perform communication protocol settings to the TOHO protocol.
- 2. In the communication changeover setting, set the channel, in which the temperature reaches the goal value latest, to the simultaneous temperature rise master, and then set the other channels to the simultaneous temperature rise slaves.
- 3. Set the main control sensitivity.
- During a simultaneous temperature rise, the slave side exerts ON/OFF control for the current temperature of the master. Accordingly, set the sensitivity to a level that does not cause chattering.

#### Note: Precautions on use

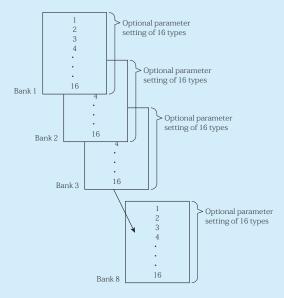
- 1. Perform auto tuning for each channel as required.
- 2. When using the simultaneous temperature rise function, do not perform communication with the outside.

#### Bank function

8 banks each with 16 setting that can be changed as optional parameter.

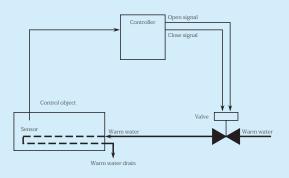
A desired state can be reached by adjusting the bank setting, but without modifying the temperature setting or valve of the PID.

This can be done by setting up a parameter for an applicable bank that references the temperature control for one unit.



#### Position proportional control

- Position proportional control
- · According to the operation amount required for PAD control, the valve opening is changed by outputting an open signal or close signal to the valve on the basis of the valve motor stroke time, so that the flow rate is adjusted, thereby controlling the target temperature. The control can be exerted without feedback resistance.
- The valve motor stroke time means the time from the full opening of the valve till its full closing.



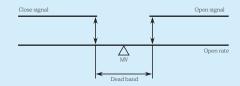
#### Valve motor drive dead band

In position proportional control, the open signal or close signal is output so that the operation amount of the regulator may agree with the opening of the valve.

It is necessary to refrain from performing an open/close changeover operation frequently in consideration of the service life of the valve.

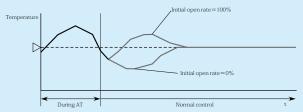
A dead band is provided at the open signal/close signal output changeover point.

In this area, both open signal output and close signal output are stopped to reduce frequent open/close changeover operations.

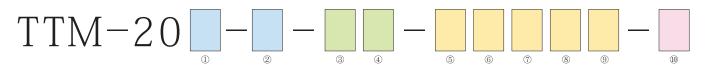


• Initial opening after the end of AT

It is possible to set the operation amount just after the end of auto tuning in order to restrict undershoot just after this end. Example) Response after the end of AT



## ■Ordering Information (Model Configurations)



эно

1	Model	4	48×48						
		5	96×48						
		7	72×72						
		9	96×96						
2	Case color	Q	Black						
		Х	Gray	Gray					
3	Output 1	N	No	J	Voltage 0 to 5VDC				
		R	Relay point of contact	F	Voltage 1 to 5VDC				
		Р	Voltage for SSR driving	G	Voltage 0 to 10VDC				
		А	Open collector	I	Current 4 to 20mADC				
		K	Voltage 0 to 1VDC	Н	Voltage 0 to 10mVDC				
4	Output 2	N	No	J	Voltage 0 to 5VDC				
		R	Relay point of contact	F	Voltage 1 to 5VDC				
		Р	Voltage for SSR driving	G	Voltage 0 to 10VDC				
		А	Open collector	Ι	Current 4 to 20mADC				
		K	Voltage 0 to 1VDC	Н	Voltage 0 to 10mVDC				
5	Output 3、4	А	Open collector			*4			
		R	Relay point of contact			*4			
6	Output 5、6	А	Open collector	Open collector					
		R	Relay point of contact			*2			
7	Output 7	А	Open collector			*1•*3			
		R	Relay point of contact (Independe	nce)					
8	AI input	Y	Multiple input (Voltage/current or	nly)		*1			
9	Option	S	CT1 input Measurement range: 0.0	CT1 input Measurement range: 0.0 to 50.0A					
	(Plural selective possibilities)	Т	CT2 input Measurement range: 0.0	*5					
		U	Event 1 input	*5					
		V	Event 2 input	*5					
		W	Event 3, 4 input (Event 3 only avail	*1•*3					
		М	Communications (RS-485)						
10	Power supply		Free power supply	Free power supply					
		L	24VAC/DC						

\*1 Not selectable for TTM-204

 $^{\ast}2$  From output 5 to 7 are not selectable for TTM-204. Output 6 is not selectable for TTM-207.

 $\ast 3$  Selectable either W (Event 3 only available) or output 7 for TTM-207.

\*4 Output 3 & 4 are common terminals for TTM-204, 205, 207 and 209.

 $^{*5}$  Combination of ST, SV and UV are only available for TTM-204 and 207.

\*6 Not selectable for TTM-205, 207 and 209.



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